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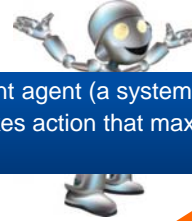
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- The Learning Process
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## Clarifying Some Definitions

### Artificial Intelligence

"The study and design of intelligent agent (a system that perceives its environment and takes action that maximize its chance of success"



### Machine Learning

Takes input empirical data → pattern recognition

Supervised Learning

### Data Mining

Focuses on discovery of unknown properties

Unsupervised Learning



## Machine Learning

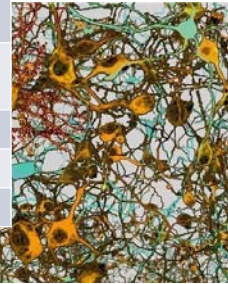
- Artificial Neural Networks (ANN)
- Support Vector Machines (SVM)
- Genetic Algorithms (GA)
- Bayesian Networks
- etc.



# Human Brain vs. Computers

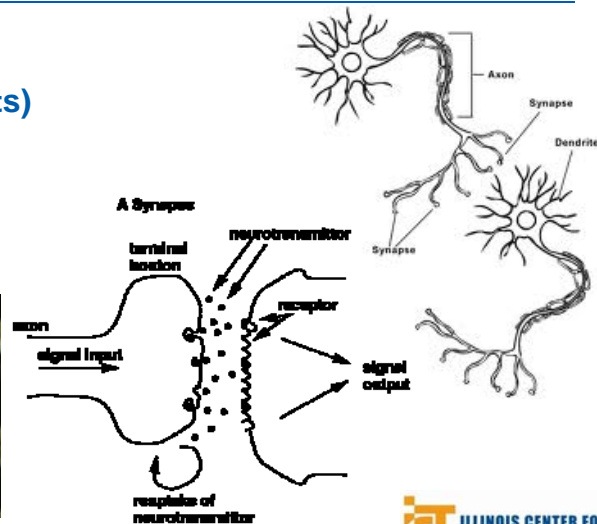
- $10^9$  ---- Each neuron connected to  $10^5$  neurons

	Brain	Computer
processing elements	$10^9$ Neurons	$10^8$ Transistors
style of computation	Parallel - Distributed	Serials - Centralized
processing speed	100 Hz	$10^9$ Hz
energy use	30 W	30 W (CPU)
Fault Tolerant	yes	no



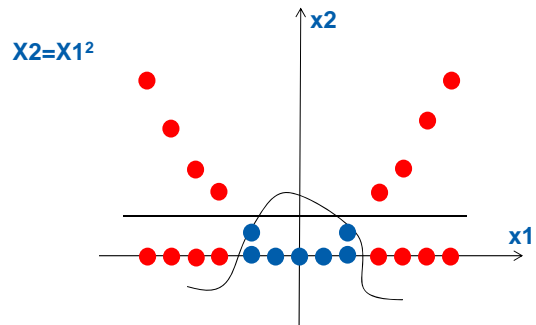
# What Happens in the Brain?

- A Neuron has;
  - Dendrites (inputs)
  - Cell Body
  - Axon (output)

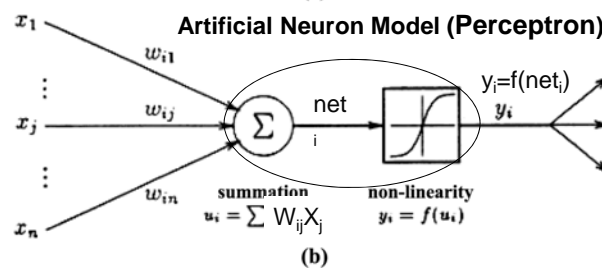
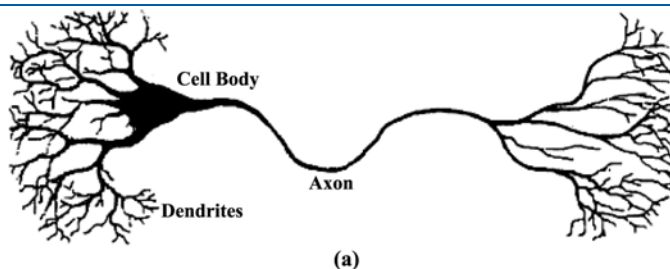


## What is Artificial Neural Network?

- ❑ Mathematical model of biological neural networks
- ❑ Non linear statistical data modeling tool



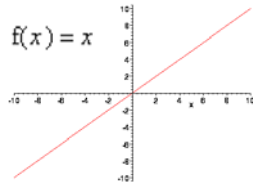
## Architecture of Neural Networks



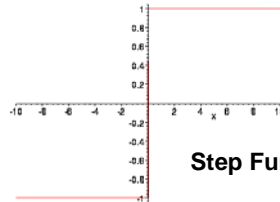
# Architecture of Neural Networks

Some activation functions;

Identity

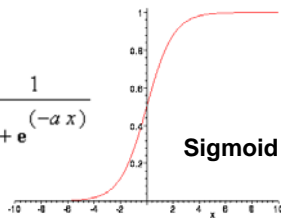


$f(x) = 0$  if  $x \leq 0$  and  $f(x) = 1$  if  $0 < x$



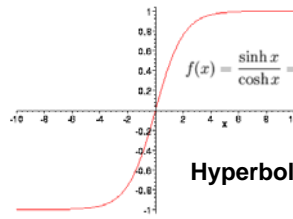
Step Function

$f(x) = \frac{1}{1 + e^{-ax}}$



Sigmoid

$f(x) = \frac{\sinh x}{\cosh x} = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{e^{2x} - 1}{e^{2x} + 1}$

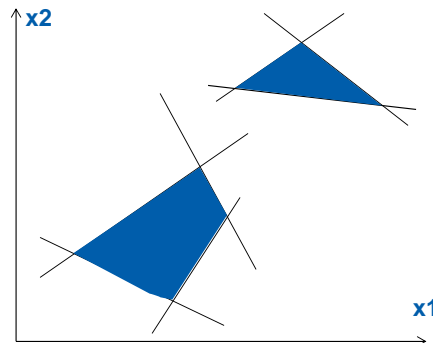
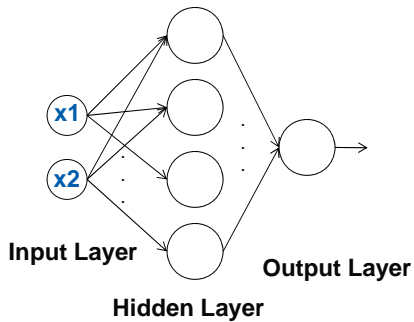


Hyperbolic Tangent



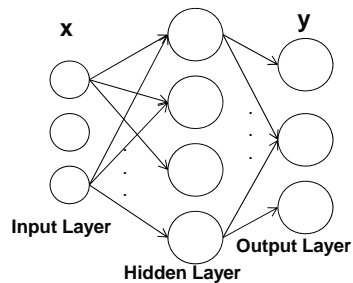
# Architecture of Neural Networks

Multilayer Perceptron



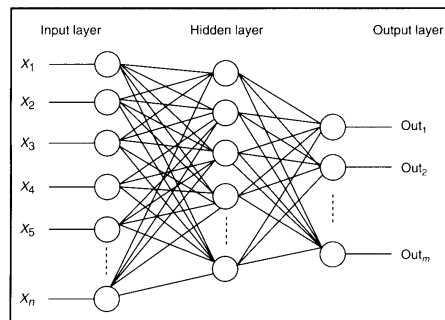
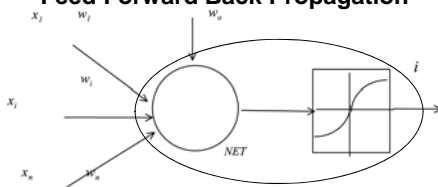
# The learning Process

- ❑ We have a set of data samples
- ❑ Each sample is an input (variables) – output(responses) pair
- ❑ In training the goal is finding the best Weights ( $W_{ij}$ )



# Training Algorithm

## Feed Forward Back Propagation



### Forward pass:

Hidden layer:

$$net_j = w_0 + \sum_i w_{ij} x_i$$

$$H_j = f(net_j)$$

Output layer:

$$net_j = v_0 + \sum_j v_{jk} H_j$$

$$Y_k = f(net_j)$$

### Error Function:

$$E = \sum_p E_p = \sum_p \frac{1}{2} (T_p - Y_p)^2$$

### Back propagation:

$$\Delta V_j = -\eta \frac{\partial E}{\partial V_j} + \alpha V_{old}$$

$$V_{new} = V_{old} + \Delta V_j$$

where  $\eta$  is the learning rate,  $\eta \in (0,1]$ , and

$\alpha$  is the momentum coefficient,  $\alpha \in [0,1]$ .

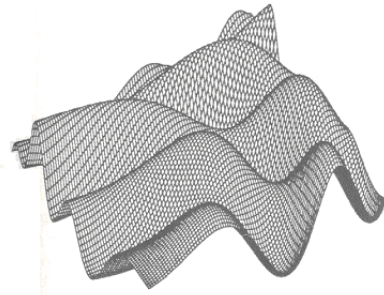
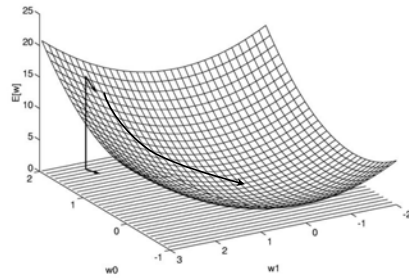
$$\Delta W_i = -\eta \frac{\partial E}{\partial W_i} + \alpha W_{old}$$

$$W_{new} = W_{old} + \Delta W_i$$

### Gradient Descent Algorithm

## Training Algorithm

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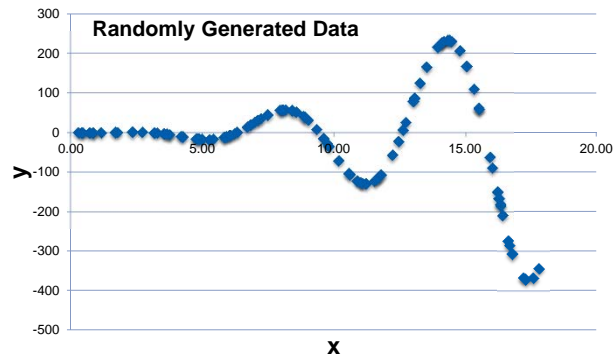
## Other Training Algorithms

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- Levenberg-Marquardt
- Conjugated Gradient
- Gauss-Newton
- Steepest Gradient
- ...

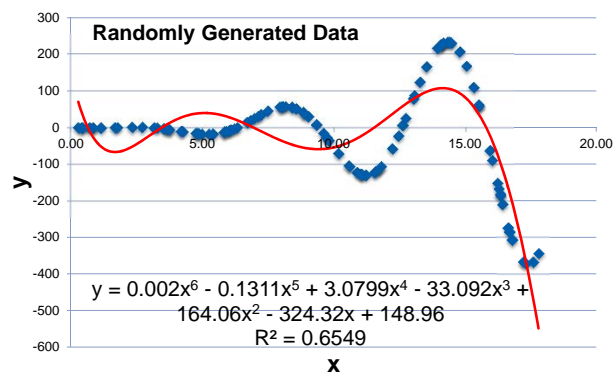
## An Example

$$y = x^2 \sin(x) \log(x)$$



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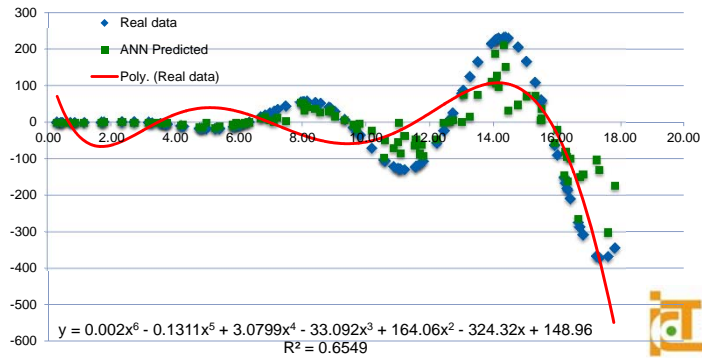
## An Example ... Training

$$y = x^2 \sin(x) \log(x)$$

80% Training  
20% Testing

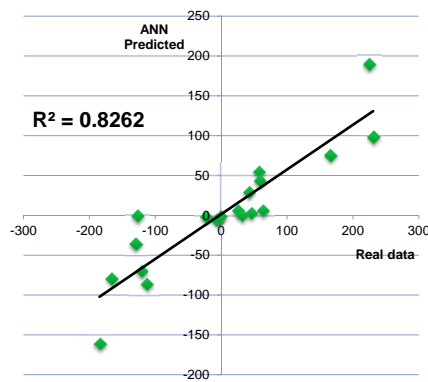
Neural Network Structure;

- MLP
- 1 hidden layer with 5 neurons
- Tanh activation function
- Training terminated at 600 iteration
- GDM training algorithm



## An Example ... Test Results

Real Data vs. ANN Predicted



Real Data vs. Polynomial Reg. Predicted

